

A Unified Batch Selection Policy for Active Metric Learning



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What makes objects similar?



Clustering

Customers Who Bought This Item Also Bought



Product recommendation



Wildlife search



Preference learning

Requires capturing humans' notion of perceptual similarity

Human supervision for metric learning



A



B



C

Does A taste more similar to B or C?

{“yes”, “no”, “can’t say”}

- Less subjective
- Less inconsistent
- Easy for human



- Annotation complexity is huge - $O(n^3)$



Active metric learning (AML) – label smarter

➤ Goal –

- To learn an effective **continuous perceptual metric** using the **minimum** possible **annotated triplets**

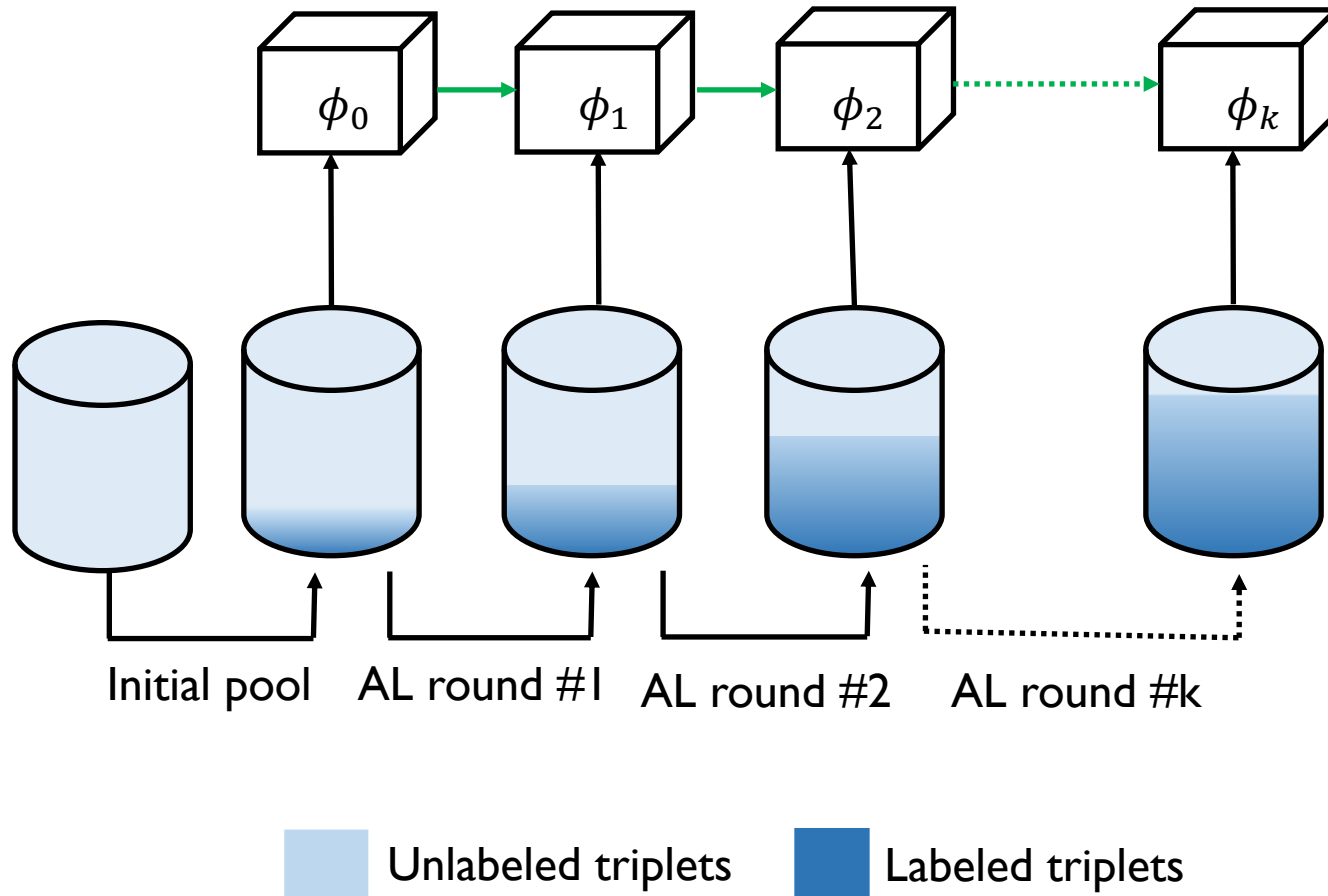
➤ Key insights –

- All triplets are not equally informative for the model
- A good model can be trained on much fewer high-utility triplets

Two stages of active metric learning

(1) **Triplet selection** - Choose a subset of most informative triplets to annotate

(2) **Model update** - Train the model on the updated training set



Which triplets are informative?

Existing work: use **single-instance uncertainty-based** informativeness measure

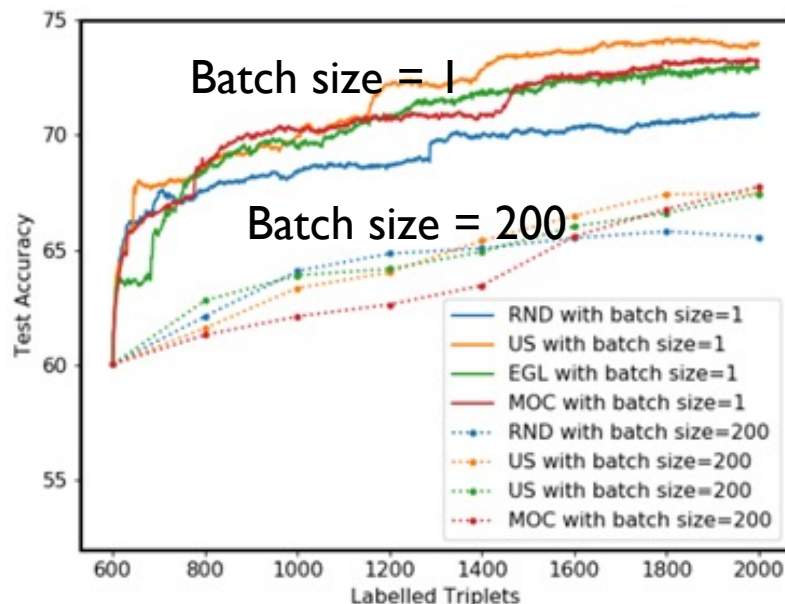
$$S^* = \operatorname{argmax}_{\{S \subset U\}} H(S) = \sum_{t \in S} H(t)$$

Overestimates collective informativeness

$$= \sum_{t \in S} \underbrace{-p_{ijk} \log p_{ijk} - p_{ikj} \log p_{ikj}}_{\text{Entropic measure}}$$

Entropic measure

In batch mode, correlation b/w triplets is a huge problem



Batch AML – diversity is necessary

Our previous work: decoupled measures for informativeness and diversity

[Kumari, Chaudhuri, and Chaudhuri IJCAI2020]

↓
Entropy

↓
Decorrelation
metrics

Separate measures **do not** ensure optimal tradeoff b/w both criteria

We proposed **joint entropy** as a **unified** measure to **jointly** balance both informativeness and diversity

$$H(S) = -\int p(x) \log p(x) dx$$

How to define $p(x)$ for a batch of triplet ?

Defining probability distribution

Priors

We characterized the probability distribution by **2nd order moments** estimated in **distance margin space** $\xi_t = d_\phi^2(x_i, x_k) - d_\phi^2(x_i, x_j)$ using **dropout** in neural network

Maximum entropy principle – **Least biased** estimate of probability distribution which **best represents the prior** state of knowledge is the one with the **maximum entropy**

$$\begin{aligned} \text{maximize}_{p(x)} & - \int p(x) \log p(x) dx \\ \text{s.t.} & \int p(x) r_i dx = m_i \end{aligned}$$

Joint probability density function, $p(x)$ of a batch of triplets that satisfies **2nd order** moment constraints and also maximizes the entropy is **multivariate Gaussian**

Optimum batch selection

Maximum informative batch $S^* = \underset{\substack{S \subset T_U \\ |S|=B}}{\operatorname{argmax}} = \frac{1}{2} \log((2\pi e)^B \det(G_S))$

↓
Covariance matrix

Optimization is NP-hard

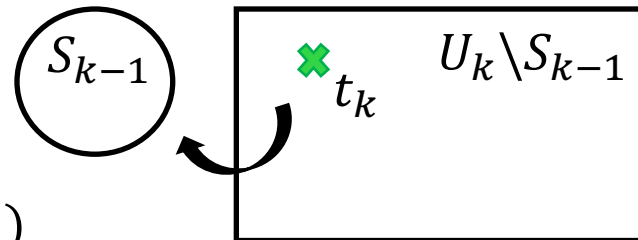
Monotone submodular optimization using greedy policy

$$S_0 = \emptyset$$

for $k = 0, \dots, B - 1$

$$t_k^* = \underset{t_k \subset U \setminus S_{k-1}}{\operatorname{argmax}} H(\{t_k\} | S_{k-1})$$

$$S_k = S_{k-1} \cup \{t_k\}$$



↓
How to efficiently compute conditional entropy?

Recursive computation of conditional entropy

Maximize conditional entropy

$$t_k^* = \operatorname{argmax}_{t_k \in U \setminus S_{k-1}} H(\{t_k\} | S_{k-1}) \rightarrow \log \left(\frac{\det(G_{S_{k-1} \cup \{t\}})}{\det(G_{S_{k-1}})} \right)$$

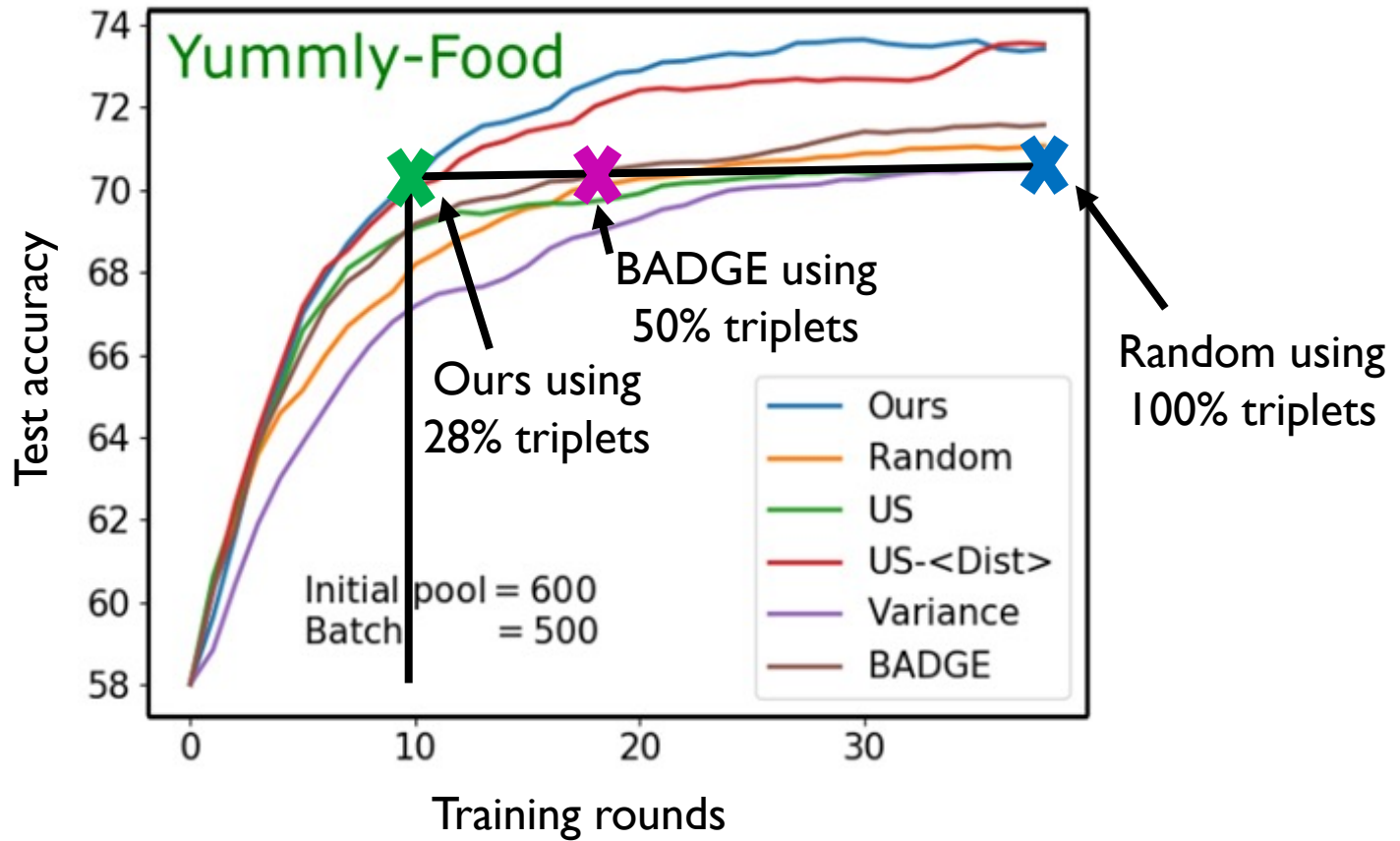
$\underbrace{\hspace{10em}}_{\|\widetilde{u}_t\|^2}$

$\|\widetilde{u}_t\|^2$ is the orthogonal projection onto span of triplet set S_{k-1}

At each step the triplet that is least correlated with the already chosen triplets

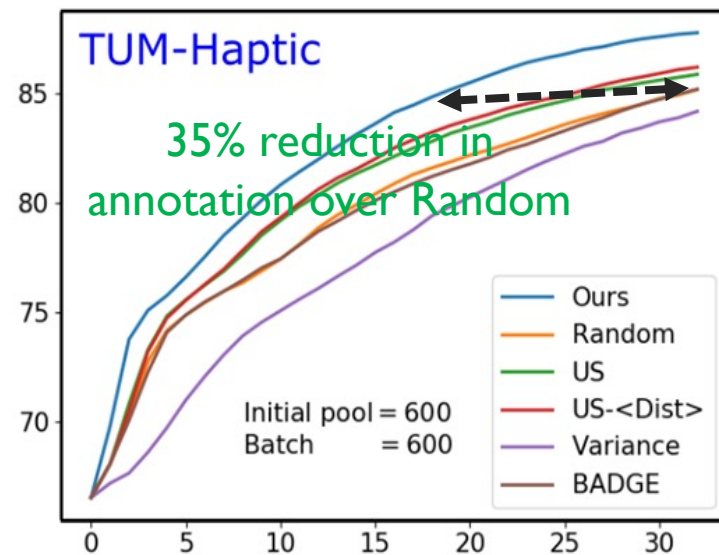
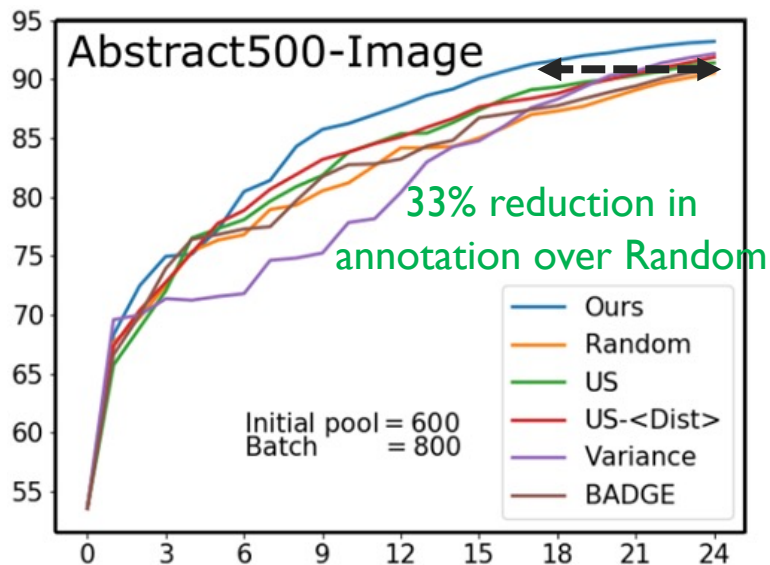
Results

72% reduction in annotation over Random

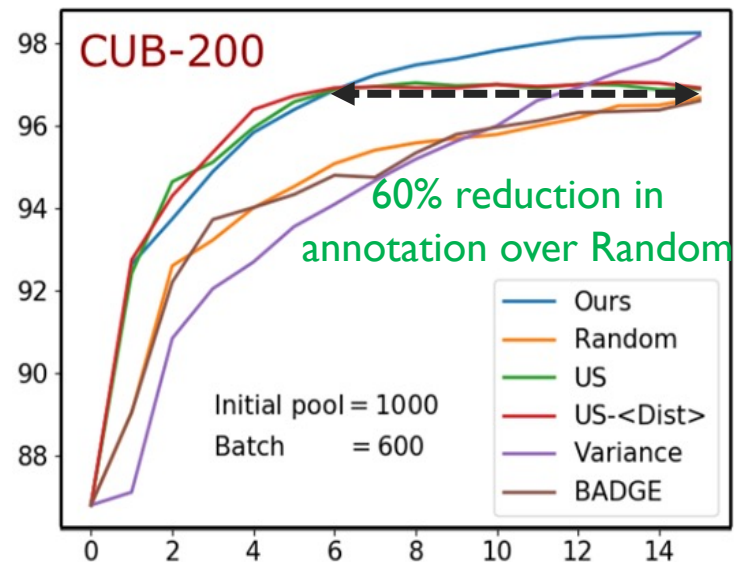


All variants of decorrelated active metric learning perform better than the Random and SoTA (BADGE)

Results



- Wide applicability across different modalities and dataset sizes
- Performance gain increases with increasing batch size



Results

Retrieved images in the order of
increasing perceptual distance



Query

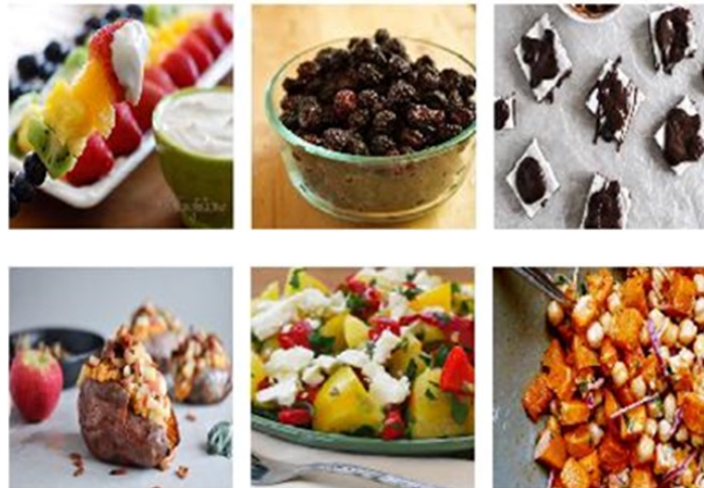


Random →
Annotate randomly-
selected batches

Ours



Query



Random

Ours

Our method gives better perceptual matches with query than randomly-selected triplets at the same annotation cost

Takeaways

- Perceptual metrics can be effectively trained on **far fewer examples** if unlabeled samples (triplets, in our case) are chosen intelligently for annotation
- **Unified measure** for informativeness and diversity is important for optimum batch selection

Future directions

- Annotation effort can further be reduced if we learn the data selection policy dynamically
- Choose not just informative samples but also informative input modality

